

## Introduction

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After its emergence in the late eighties, MEMS (Micro-Electro-Mechanical-Systems) or MST (Microsystems Technology) has developed into billion \$ commercial markets, in particular in the automotive, medical, and telecommunication fields. The Lecture Series will address applications in the aerospace field, which encounter unique challenges related to harsh environment conditions and reliability requirements. This Introduction will provide a brief introduction into the MEMS technology, discuss examples of commercial and potential aerospace applications, and introduce the lectures, which will focus on six specific aerospace applications.

MEMS are miniature devices, which integrate actuators, sensors, and processors to form intelligent systems. Functional sub-systems could be electronic, optical, mechanical, thermal or fluidic. MEMS are characterized by their close relationship to integrated-circuit components both in terms of manufacturing techniques and their potential for integration with electronics. One example of a true MEMS system, which will be discussed, is the “Smart Micro Skin” which combines sensors, actuators, and controller to detect and control flow separation at the leading edge of a delta wing.

Several manufacturing techniques are required to develop MEMS, including surface micromachining. In this process mechanical microstructures are fabricated on the surface of a wafer by depositing different types of layers. Deposited layers include structural layers, which form the final structures, and sacrificial layers, which are removed in the final stage of the fabrication through the edging process.

The advantages of MEMS are numerous. They include miniaturization (allowing distributed sensing and actuation coupled with redundancy), reduced cost of fabrication (through the use of microelectronics processing technologies), and real-time control (allowing on-line active process control and health monitoring). In addition, micro devices can control macro systems by using natural physical amplification characteristics of the system. For example, the control of flow separation at the leading edge of delta wings by micro actuators allows the control of the leading-edge-vortex position, which determines lift and moments.

Examples for MEMS commercial applications, which will be discussed, include digital micro mirrors for projectors and micro total analytical systems.

Many MEMS aerospace and military applications are being considered. Examples are micro jet arrays for flow control, IMUs (Inertial Measurement Units) for inertial measurement and navigation, fuze/safety and

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27-28 February 2003; Monterey, CA, USA, 3-4 March 2003, and published in RTO-EN-AVT-105.*

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## Introduction

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arming for munitions, health monitoring of machinery, and telecommunication for pico satellites. The MEMS aerospace applications are confronted with barriers and challenges, which are more severe than for commercial applications. This resulted in slow progress of inserting many of the potential MEMS aerospace applications.

Military MEMS applications are being addressed in the NATO RTO (Research and Technology Organization) MEMS Task Group AVT (Applied Vehicle Technology) –078. This Group is assessing potential applications, determining technology status and R&D needs, discussing barriers for implementation, and developing insertions strategies. The Task Group saw the need to enhance user and MEMS supplier interactions and to increase MEMS awareness as enabling technology for several applications. Because of this need, the Task Group has proposed these Lecture Series, which will provide an introduction into MEMS technology and then focus on six potential applications, namely micro-flow control, IMU, fuze/safety & arming, micro power, gas turbines applications, inventory and health monitoring of munitions. Also an introduction into MOEMS (Micro-Optical-Electro-Mechanical-Systems) will be provided.

# **INTRODUCTION**

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## **RTO LECTURE SERIES “MEMS AEROSPACE APPLICATIONS”**

MONTREAL, CANADA, 3/4 OCTOBER 2002

ANKARA, TURKEY, 24/25 FEBRUARY 2003

BRUSSELS, BELGIUM, 27/28 FEBRUARY 2003

MONTEREY, CA., USA, 3/4 MARCH 2003

# OUTLINE

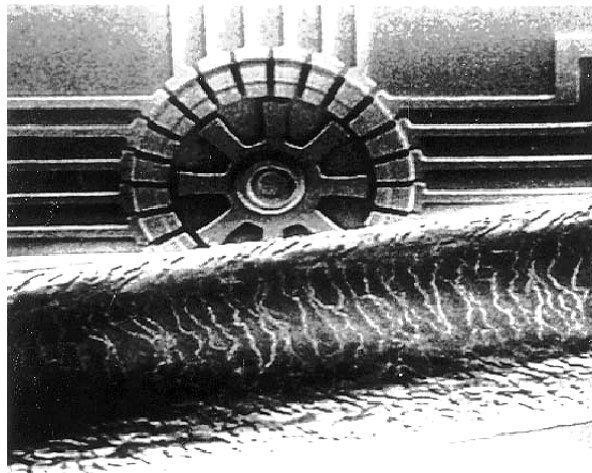
- FROM CURIOSITY TO BILLION \$ MARKETS
- WHAT IS MEMS?
- WHY MEMS?
- EXAMPLES OF COMMERCIAL APPLICATIONS
- POTENTIAL AEROSPACE APPLICATIONS
- BARRIERS AND CHALLENGES FOR IMPLEMENTATION
- SELECTED AEROSPACE APPLICATIONS

# FROM CURIOSITY TO BILLION \$ MARKETS

- 1960
  - MICROSENSORS
- 1980
  - MICROACTUATORS
- 1988
  - MEMS
- 2002
  - (INKJETS)
  - AUTOMOTIVE SYSTEMS
  - BIOMEDICAL SYSTEMS
  - TELECOMMUNICATION

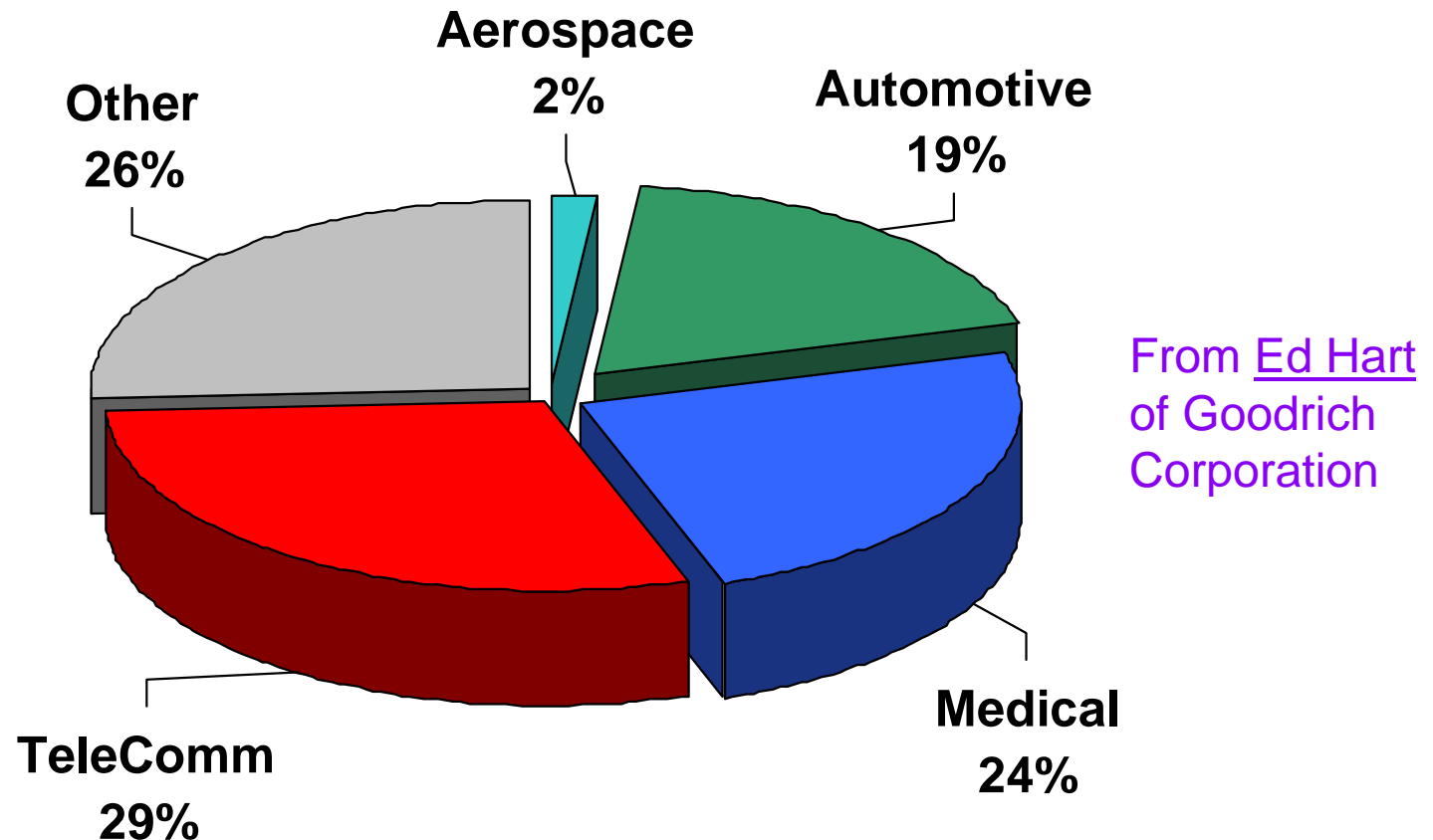
# FIRST MICRO MOTOR

*Micro-Electro-Mechanical -System*  
*MEMS*



UC BERKELEY, 1988

# Global Market Segments



**MEMS Component Sales in 2000: \$3 Billion**  
**Projected 5 Year CAGR: 60%**

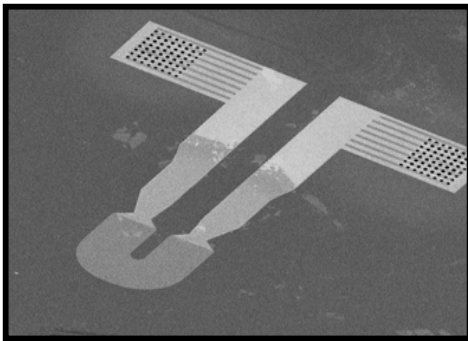


# WHAT IS MEMS?

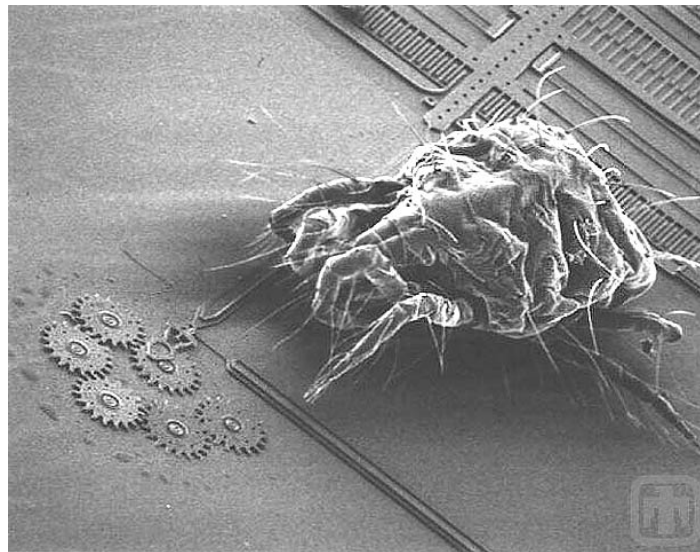
- MICRO-ELECTRO-MECHANICAL-SYSTEMS
  - MINIATURE DEVICES
  - INTEGRATION OF ACTUATOR, SENSOR, CONTROLLER / PROCESSOR
  - ELECTRONIC, OPTICAL, MECHANICAL, THERMAL AND / OR FLUIDIC FUNCTIONALITY
- WAY OF MAKING THINGS (DARPA)
  - INTEGRATED-CIRCUIT (IC) BASED MANUFACTURING TECHNIQUE AND INTEGRATION WITH ELECTRONICS
  - MICROMACHINING
- MICROSYSTEMS TECHNOLOGY

# MEMS Components

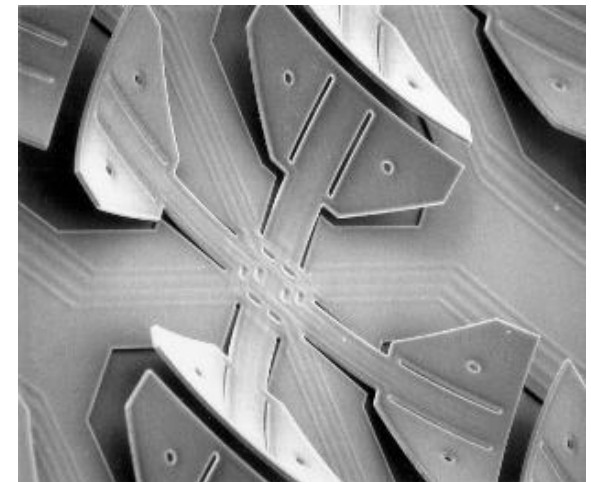
**MEMS-based systems are physically small and integrate electrical and mechanical components.**



Sensors



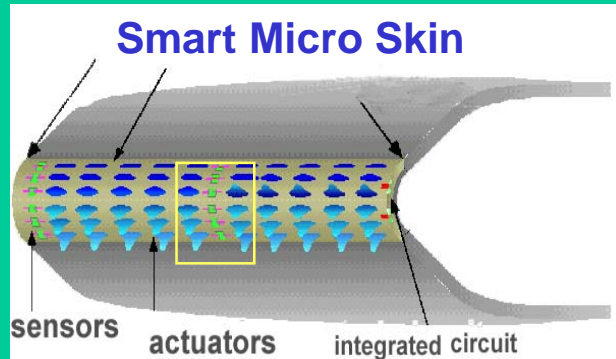
Mechanisms



Actuators

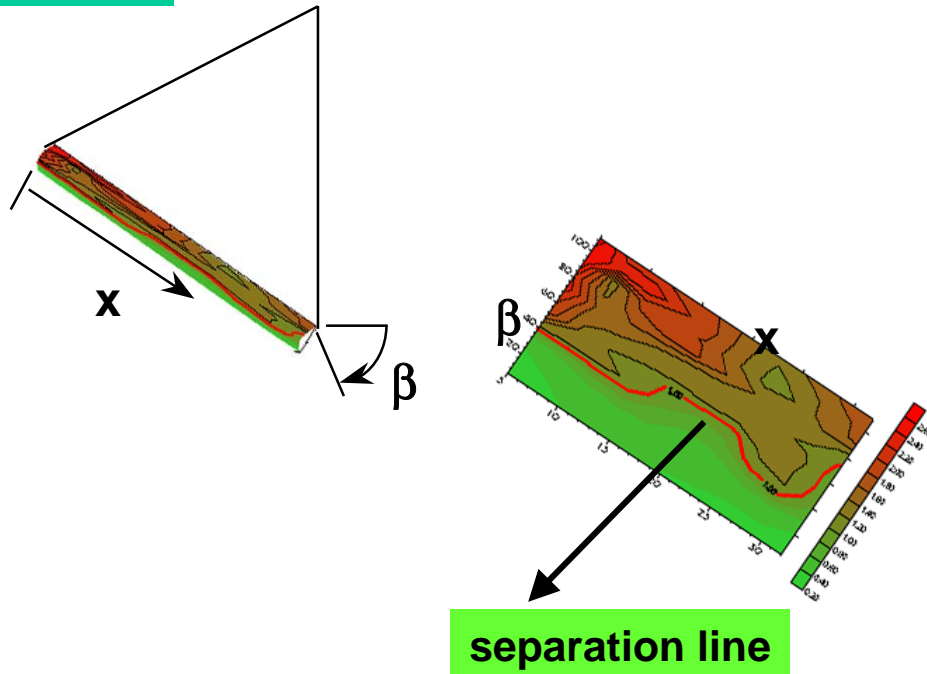
## *Sensing and actuation at L.E.*

### Sensor, I.C's & Actuator

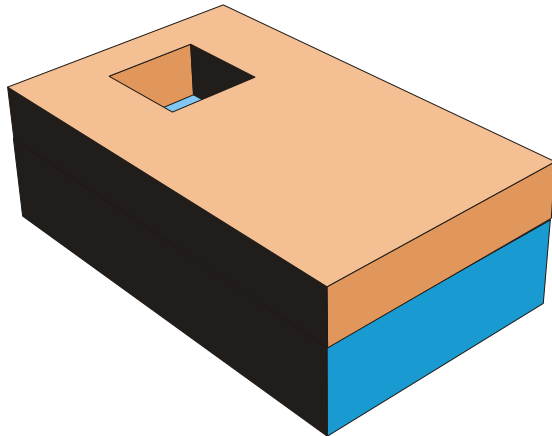


***L.E.***

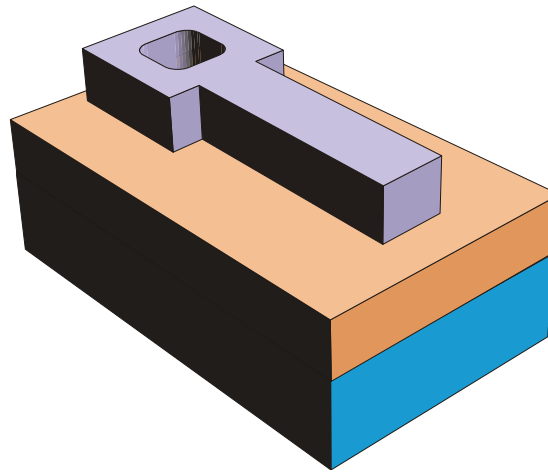
***Small area - micro transducers  
Curved surface***



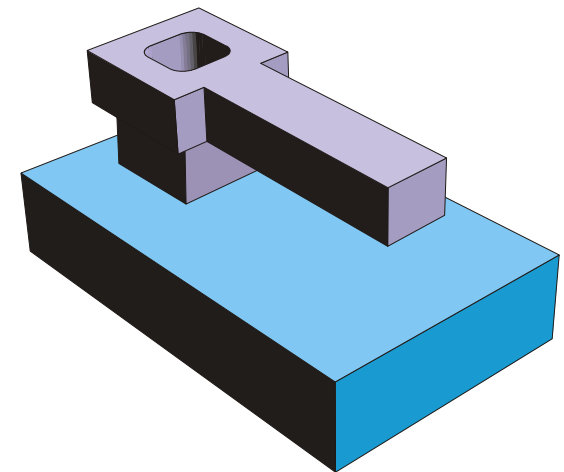
# Surface Micromachining



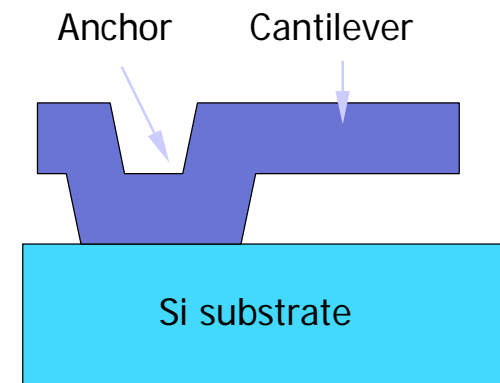
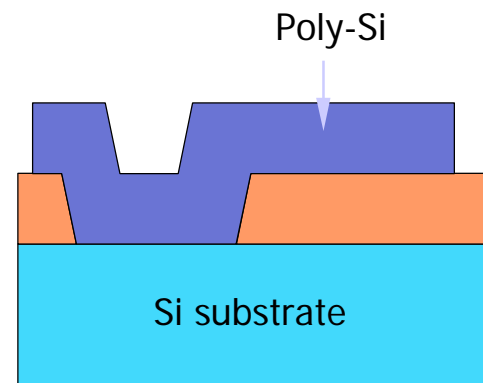
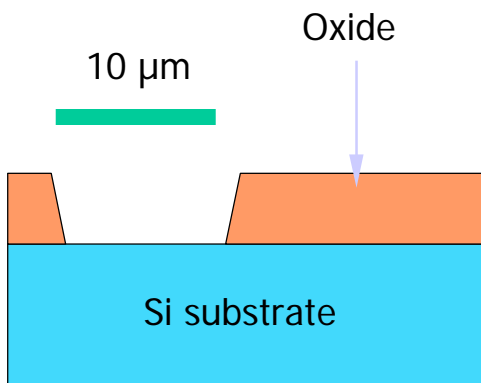
*Deposit & pattern oxide*



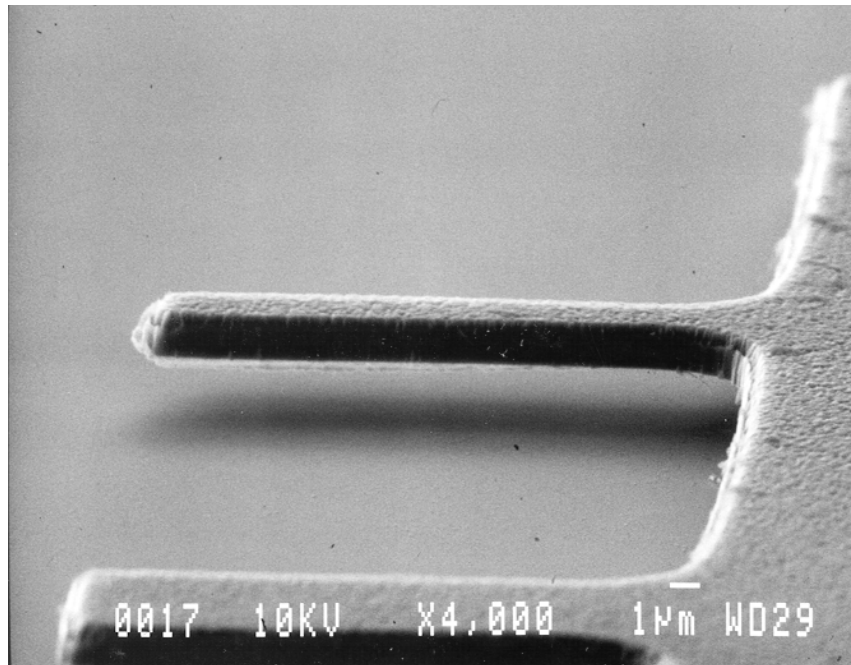
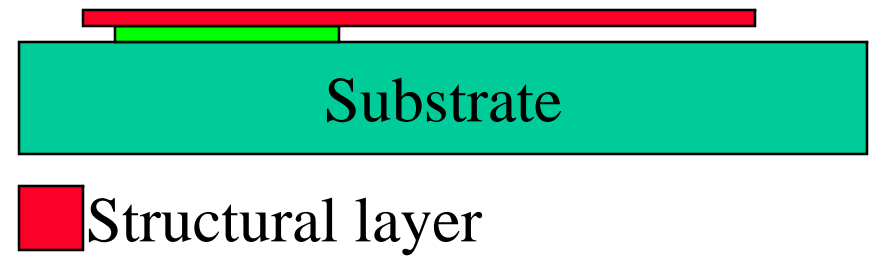
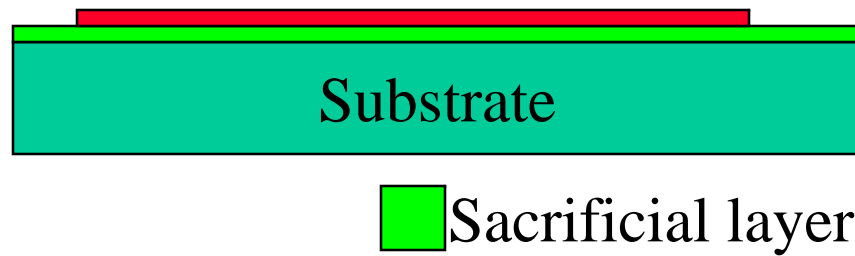
*Deposit & pattern poly*



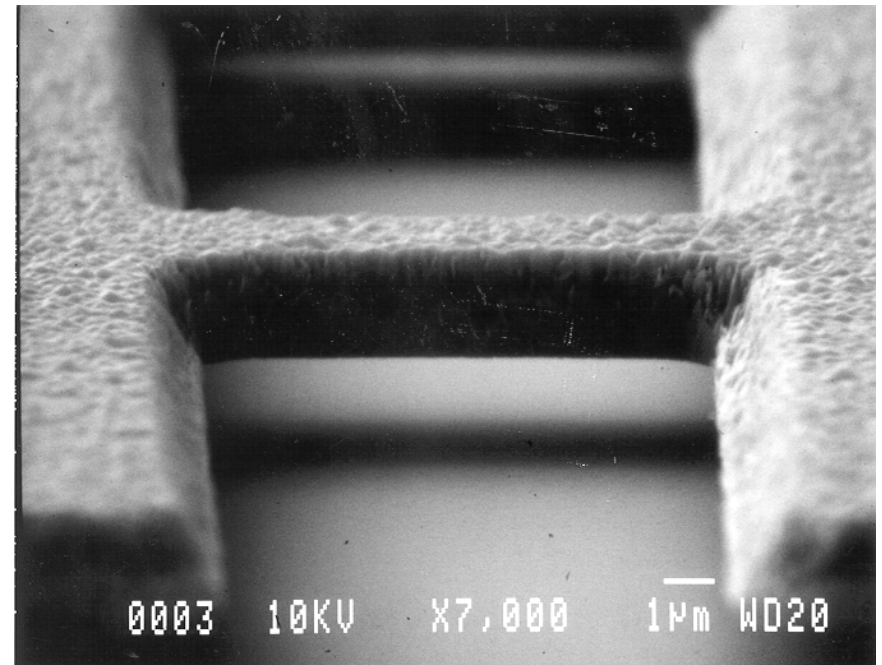
*Sacrificial etch*



# Simple Surface-Micromachined Structures



**Cantilever beam**



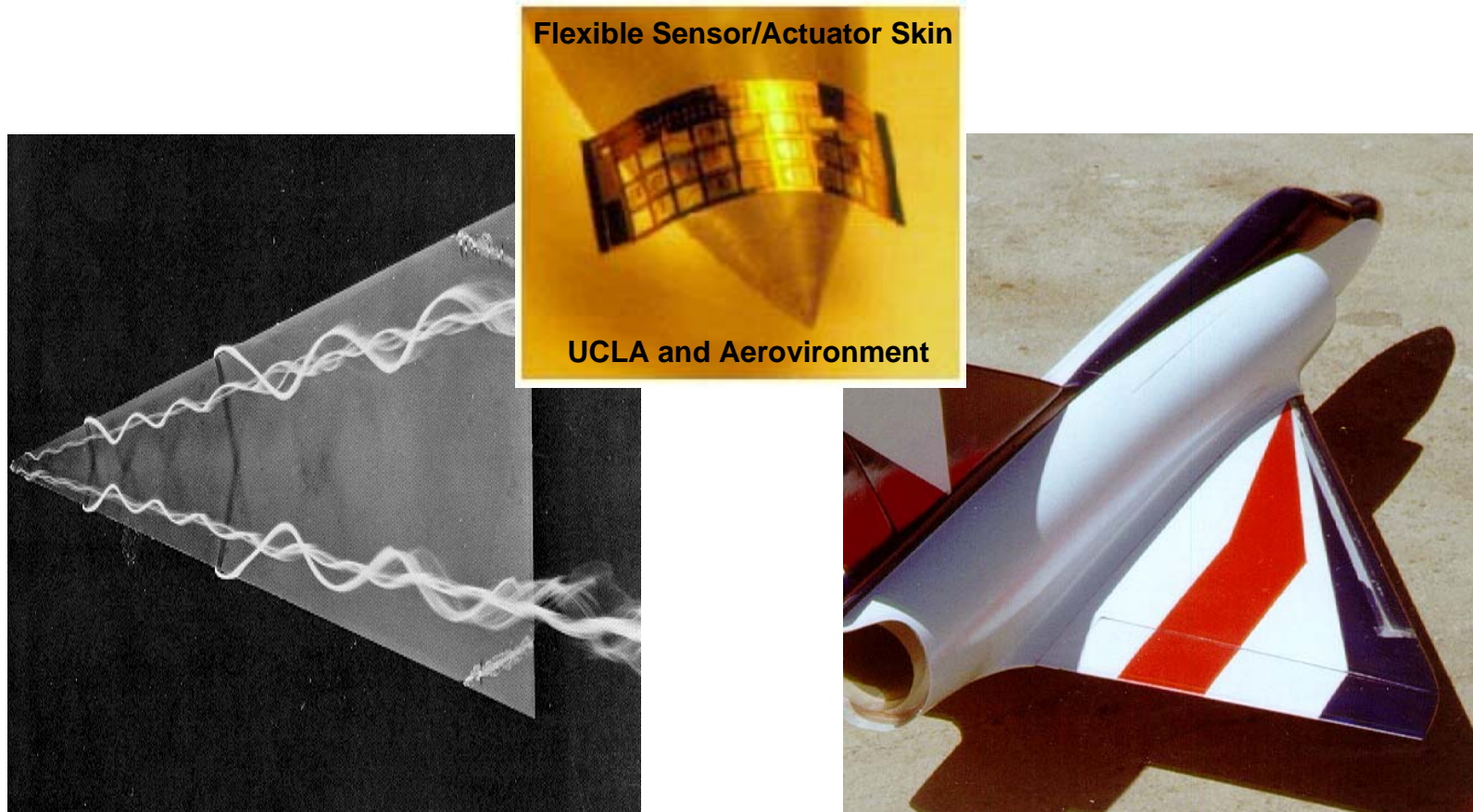
**Doubly-supported beam**

## WHY MEMS?

- MINIATURIZATION
  - DISTRIBUTED SENSING AND ACTUATION COUPLED WITH REDUNDANCY
- REDUCED COST OF FABRICATION
- REAL TIME CONTROL
  - ON-LINE ACTIVE PROCESS CONTROL AND HEALTH MONITORING
- MICRO DEVICES CONTROL MACRO SYSTEM



# MEMS Actuators for Aero Control



## MEMS Actuator Array on the Leading Edge of Wing of 1/7 Scale Mirage III Fighter



Microsystems Technology Office

Approved for Public Release - Distribution Unlimited

*UCLA and Aerovironment*

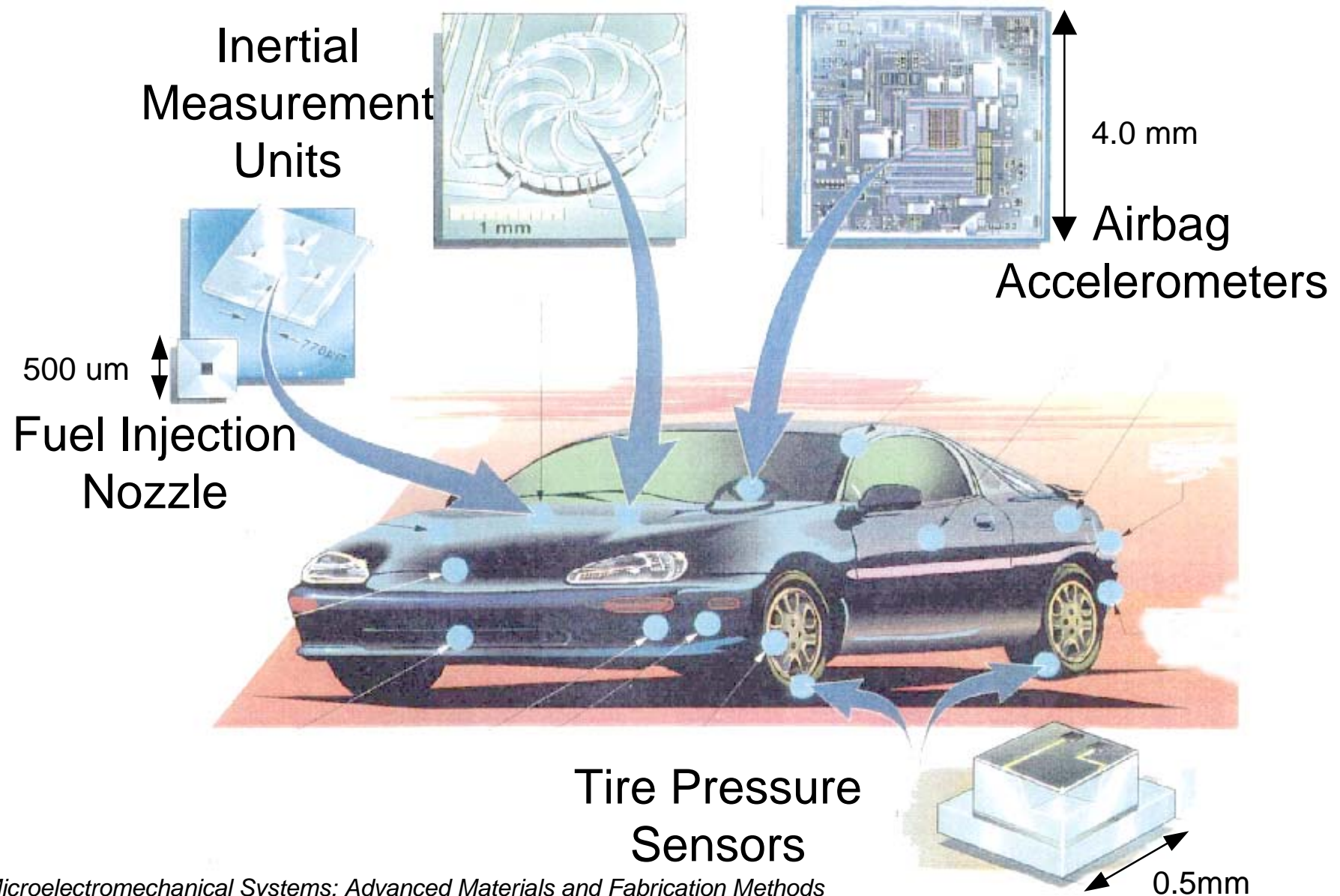
I-12

## COMMERCIAL APPLICATIONS

- AUTOMOTIVE MEMS SYSTEMS
- OPTICAL MEMS
- MICRO TOTAL ANALYTICAL SYSTEMS (TAS)
- COMMUNICATION / RF MEMS
- BioMEMS
- INSPECTION MEMS

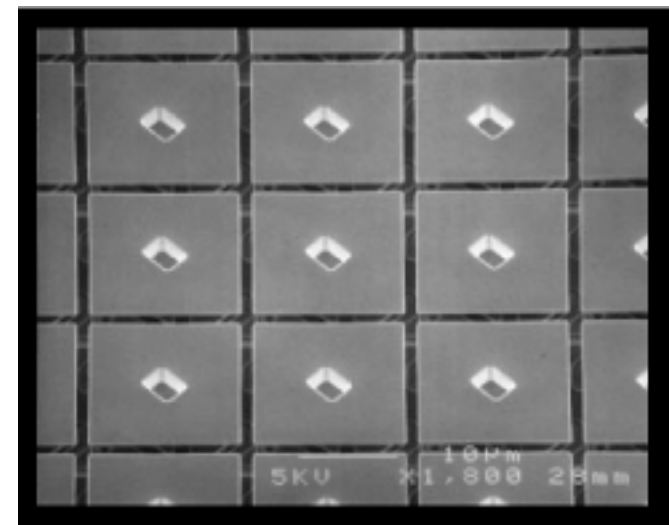
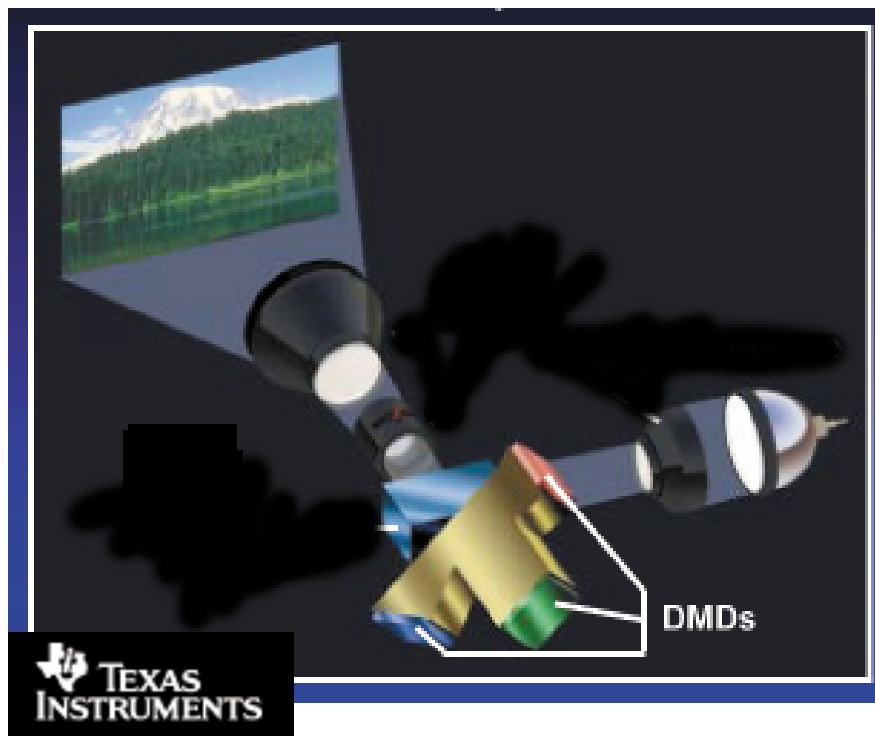


# Commercial MEMS-based Products



*Microelectromechanical Systems: Advanced Materials and Fabrication Methods*

## Digital Micromirrors for Sub-portable Projectors



10 µm

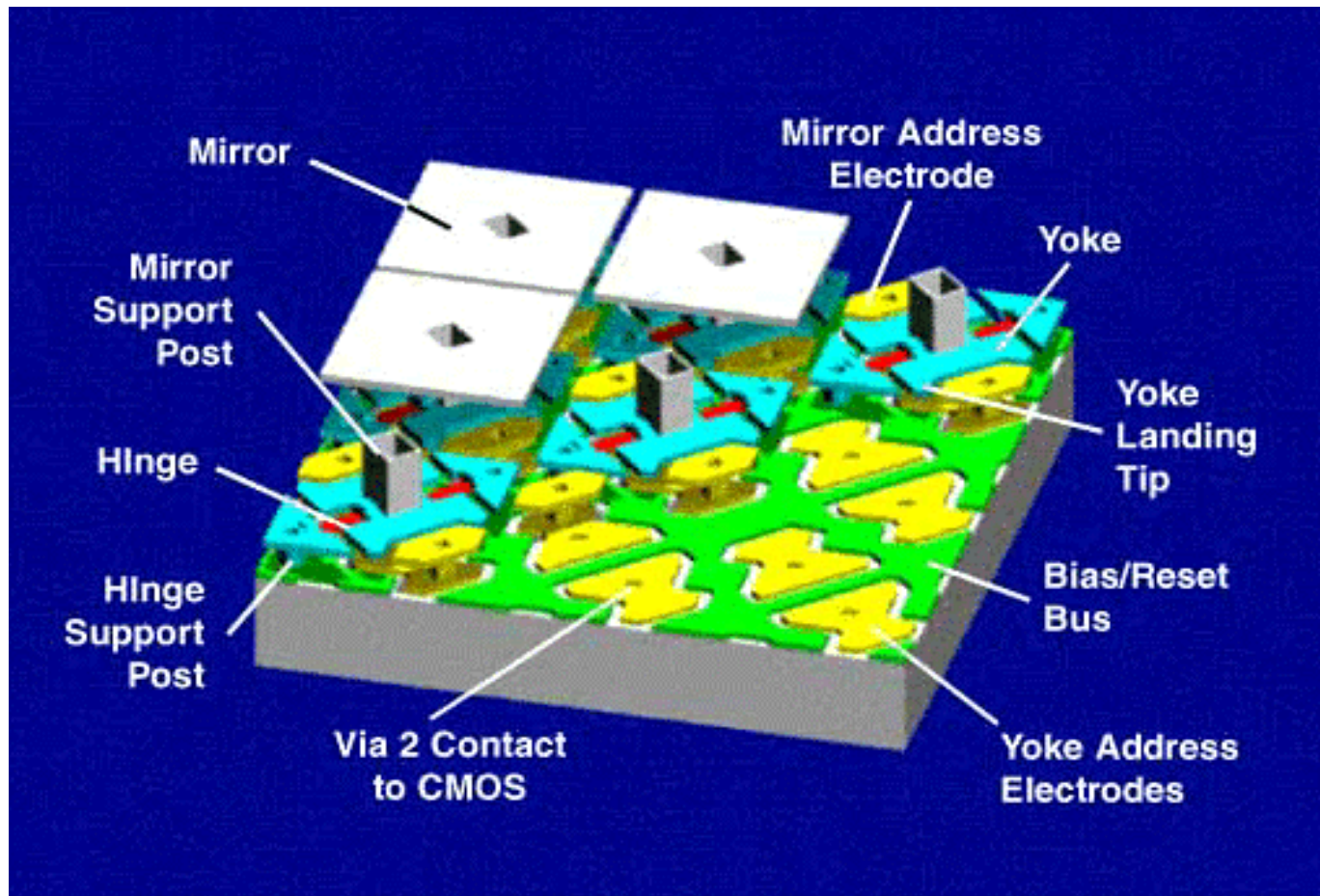


### **PLUS U3-880**

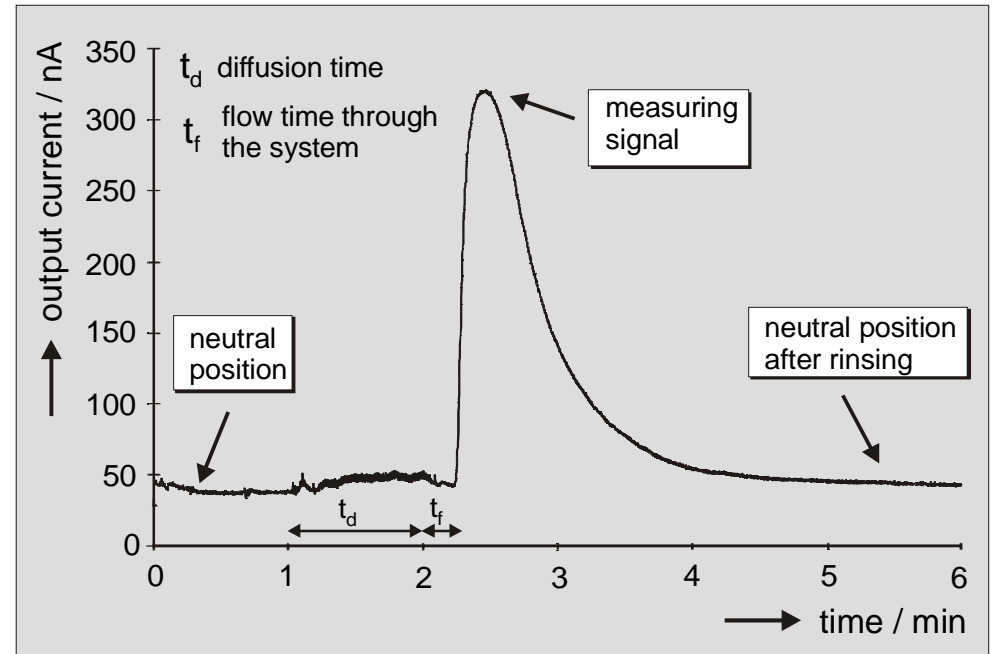
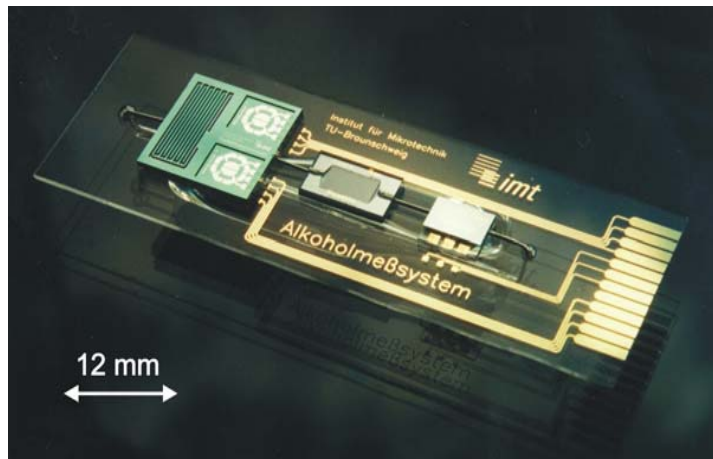
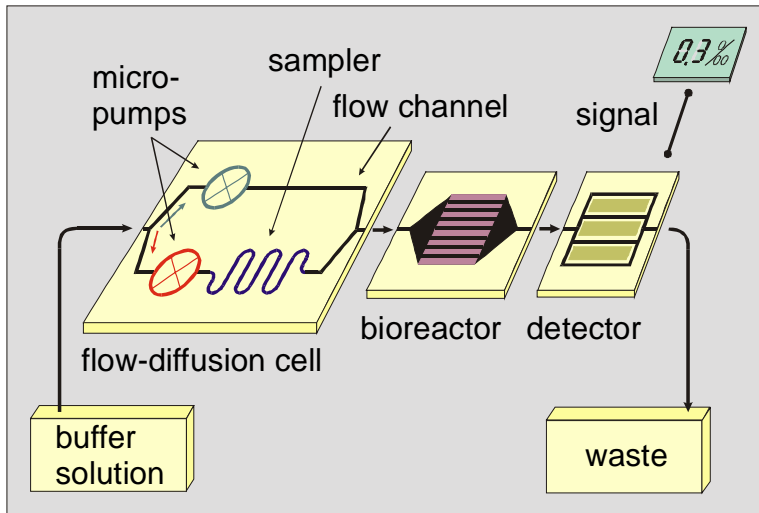
- 2.9 lbs
- 1.9" x 9" x 7"
- SVGA (800 x 600)

# Digital Mirror Display (DMD)

Texas Instruments, Inc.



# Micro flow-diffusion analysis system

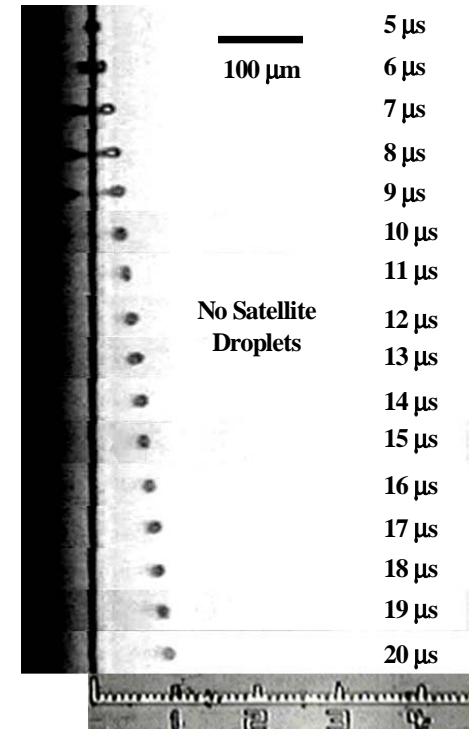
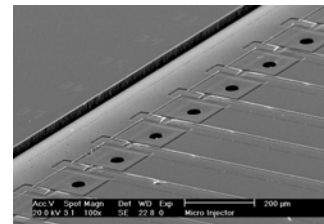
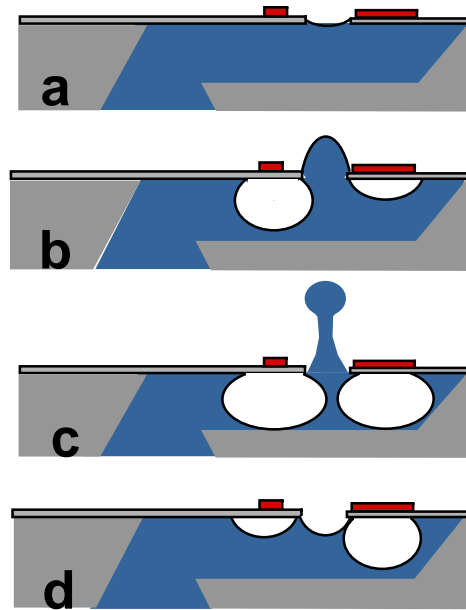
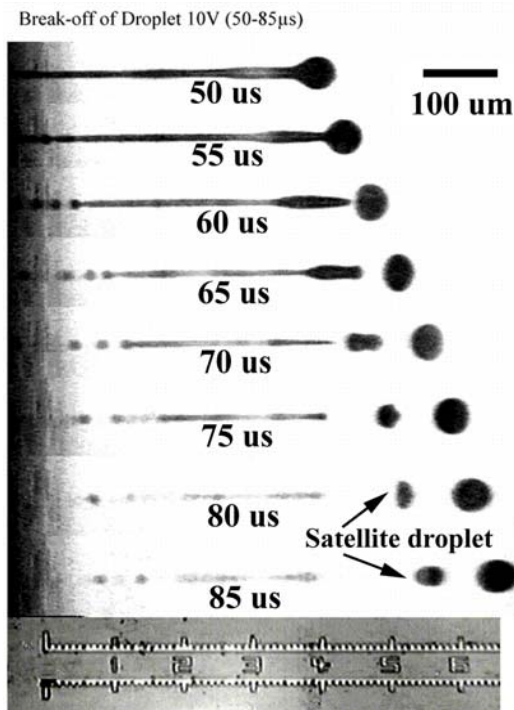
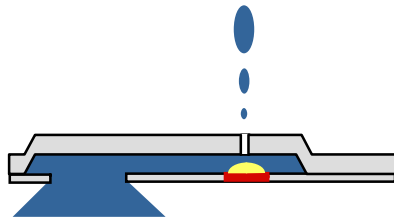


Transcutaneous measurement of blood alcohol  
20 minutes after drinking of two glasses of  
champagne

Further application: non-invasive measurements  
of metabolites as indicators of the physical  
condition



# Precision Delivery of Minute Amount of Liquid



**10 micron droplet  
30kHz**

**0.5 pico-litter**

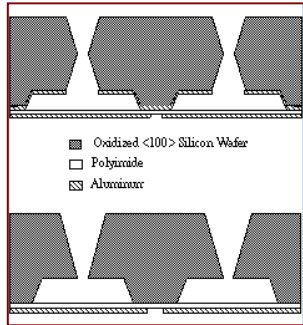
- High resolution printing
- Drug delivery

**Kim, Ho**

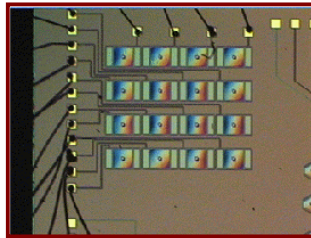
## AEROSPACE MEMS APPLICATIONS WITH “HIGH-END” FUNCTIONALITY

- Complete inertial and navigation units on a single chip.
- **Inertial Measurement Units (IMU) on a chip.**
- **Distributed sensing systems for monitoring, surveillance and control.**
- Miniature and integrated fluidic systems for instrumentation and bio-chemical sensors.
- Embedded sensors and actuators for maintenance and monitoring.
- **Identification and tagging systems using integrated micro-opto-mechanical MEMS.**
- Smart structures and components.
- **Micro flow control**
- **Fuze / Safety & Arming**
- **Micro Power and Propulsion**
- Mass storage and novel display technologies.

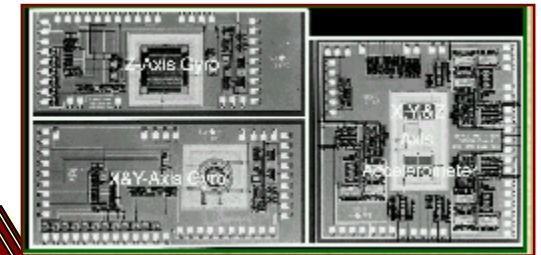
# MEMS for Military Applications



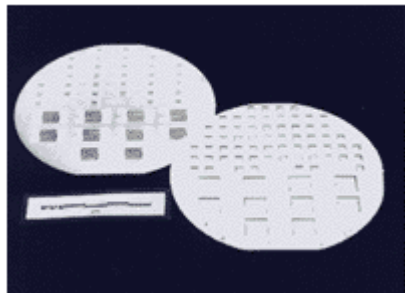
Microjet Arrays  
for Airflow Control



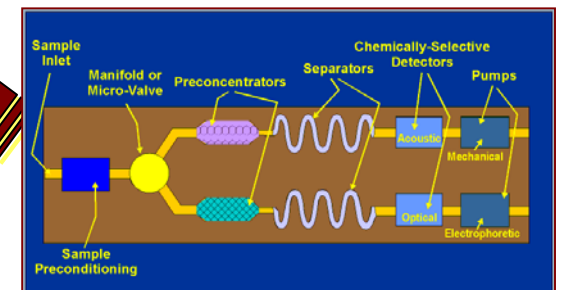
Adaptive Optics Arrays  
for Target Acquisition &  
Friend or Foe ID



MEMS IMU  
for Inertial Measurement  
& Navigation



Multiple Chip Wafer Fabrication  
for Graceful Degradation and Cost  
Reduction



Chem-Lab on a Chip  
for Forward Recon & QA



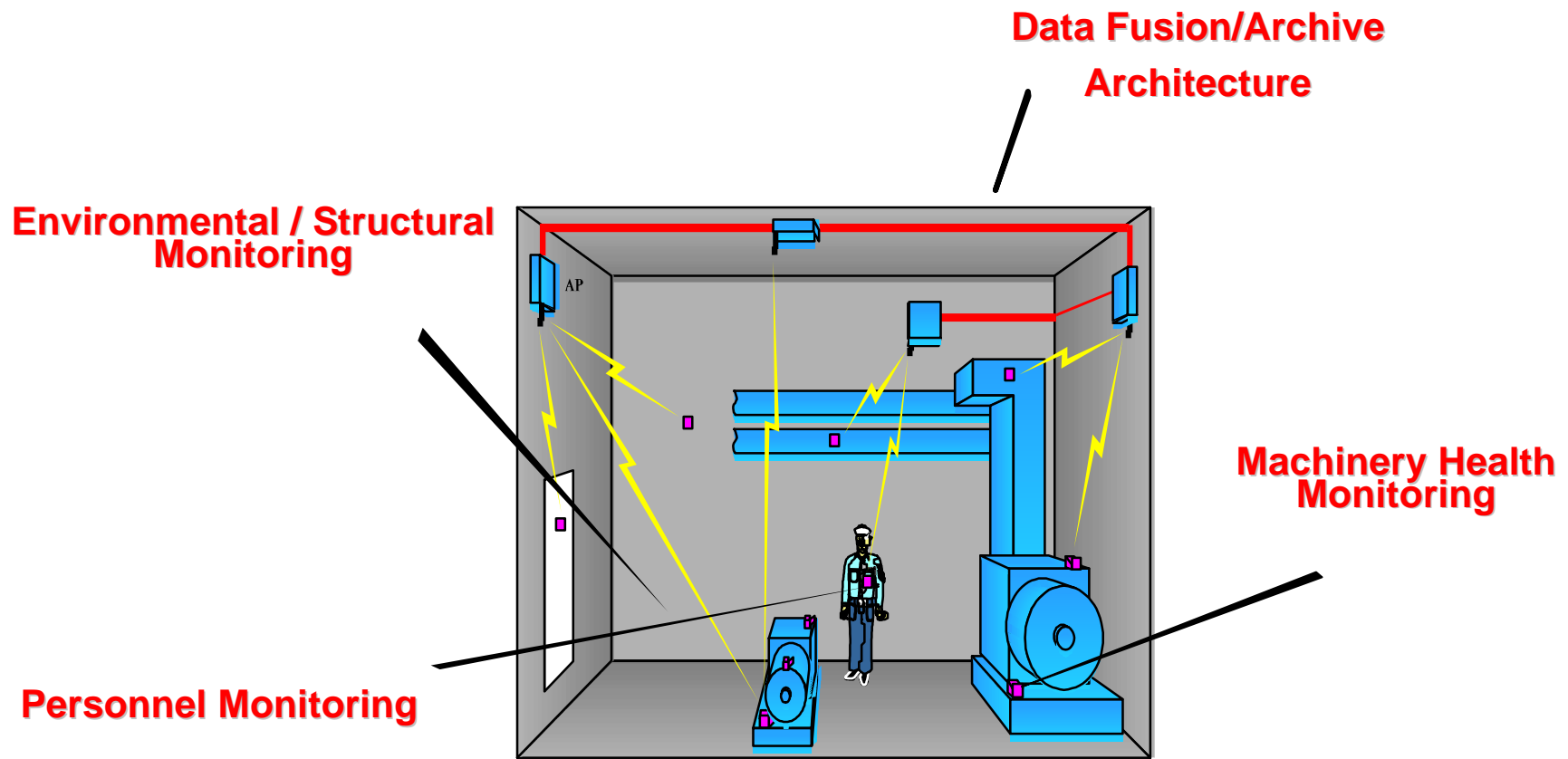
Fuze/safety  
and arming



# Reduced Ship's Crew by Virtual Presence (RSVP) Concept



## Internal Ship Situational Awareness





## BARRIERS AND CHALLENGES FOR IMPLEMENTATION

- RELIABILITY
- HARSH ENVIRONMENT
- SUPPLY AVAILABILITY
- OBSOLESCENCE
- PACKAGING
- MANUFACTURING
- LACK OF STANDARDS
- SECURITY ASPECTS

# NATO RTO/AVT MEMS TASK GROUP

- APPLICATIONS, STATUS, R&D NEEDS, BARRIERS
- 2000 to 2003
  - INTERIM REPORTS, CDs FROM 3 MEETINGS
  - FINAL REPORT, SEPTEMBER 2004
  - RTO SYMPOSIUM, BRUSSELS, APRIL 2003
- FOCUS
  - HEALTH MONITORING
    - GAS TURBINES
    - MUNITIONS
  - IMU
  - MICRO FLOW CONTROL
  - FUZE/SAFETY&ARMING
  - MICRO POWER

## **RLS “MEMS AEROSPACE APPLICATIONS” First Day**

<b>08:15-08:45</b>	<b>Registration</b>
<b>08:45-09:00</b>	<b>Opening Ceremony, National Authorities</b>
<b>09:00-09:30</b>	<b>Dr. Klaus C. Schadow, Consultant, US, “Introduction”</b>
<b>09:30-10:30</b>	<b>Prof. Dr. Mehran Mehregany, Case Western Reserve University US, “Introduction into MEMS Technology (1)”</b>
<b>10:30-11:00</b>	<b>Break</b>
<b>11:00-11:30</b>	<b>Prof. M. Mehregany, US, “Introduction into MEMS Technology (2)”</b>
<b>11:30-12:30</b>	<b>Dr. Clyde Warsop, BAE SYSTEMS, UK, “Micro-Flow Control (1)”</b>
<b>12:30-14:00</b>	<b>Lunch</b>
<b>14:00-15:15</b>	<b>Dr. Warsop, UK, “Micro-Flow Control (2)”</b>
<b>15:15-15:45</b>	<b>Break</b>
<b>15:45-16:45</b>	<b>Prof. M. Mehregany, US, “Applications to Gas Turbines – Health Monitoring”</b>
<b>16:45-17:15</b>	<b>Dr. K. Schadow, US, “Micro Power”</b>

## **RLS “MEMS AEROSPACE APPLICATIONS” Second Day**

<b>08:45-10:00</b>	<b>Dr. Ayman El-Fatetry, BAE STSTEMS, UK, “Inertial Measurement Units - IMU”</b>
<b>10:00-10:30</b>	<b>Break</b>
<b>10:30-11:30</b>	<b>Dr. A. El-Fatetry, UK, “MOEMS”</b>
<b>11:30-12:45</b>	<b>Paul Smith, IHDIV, Naval Surface Warfare Center, US, “Fuze/Safety &amp; Arming”</b>
<b>12:45-14:00</b>	<b>Lunch</b>
<b>14:00-15:00</b>	<b>Paul Smith, US, “Health Monitoring of Munitions”</b>
<b>14:00-14:30</b>	<b>Wrap-Up</b>